

Measures of Precision

Overview

- How to quantify uncertainty
- Why variance is important
- Components of variation in distance sampling
- Controlling variance
- Estimating variance
 - Analytic
 - Bootstrap
- Confidence Intervals

How do estimates behave?

Consider an artificial population

$D = 500$ per unit² (no density gradient)

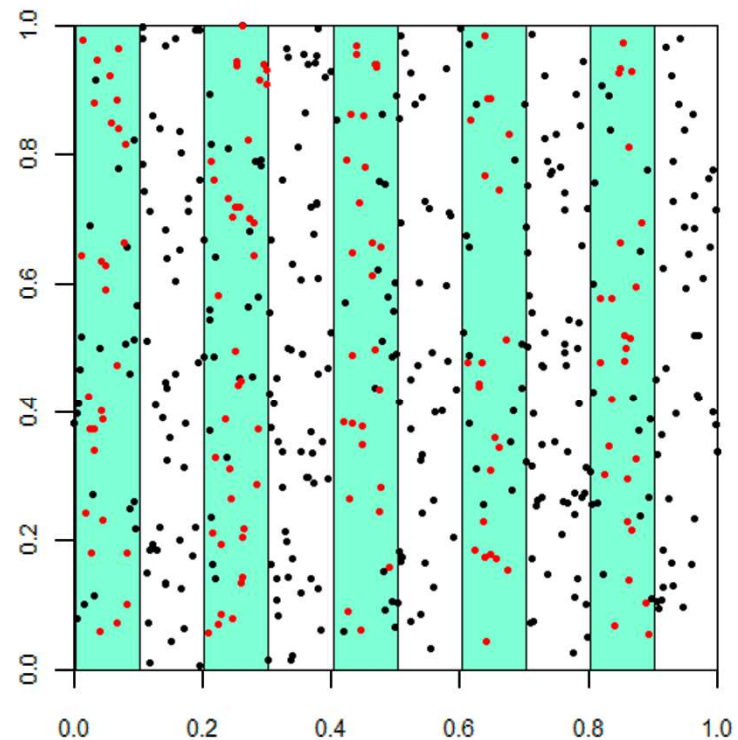
Design: 5 transects equally-spaced
($w=0.05$)

Results:

$$n = 140$$

$$\hat{f}(0) = 34.6$$

$$\hat{D} = 484.4$$



How do estimates behave?

Consider a duplicate survey

Same population model

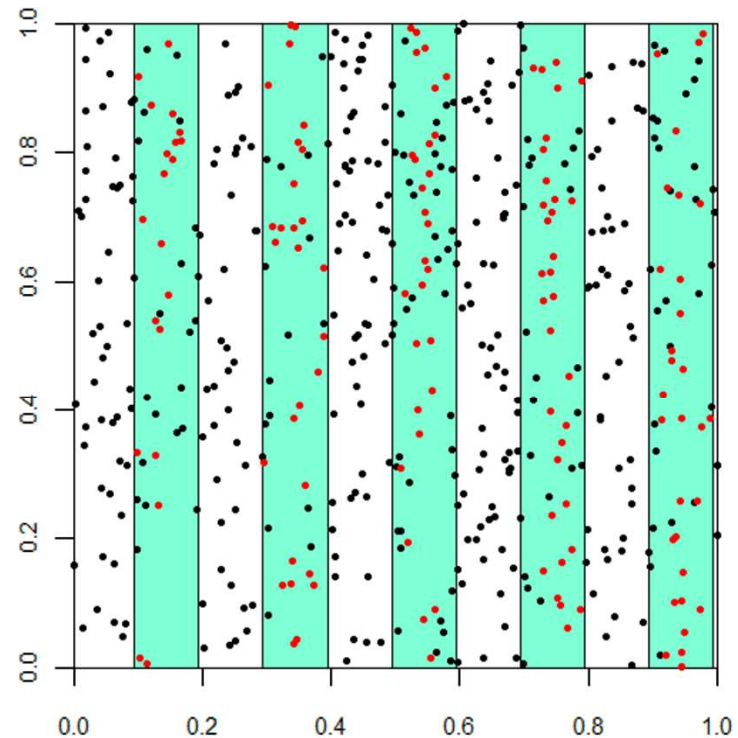
Same survey design (with a new random start point)

Results:

$$n = 139$$

$$\hat{f}(0) = 37.6$$

$$\hat{D} = 522.1$$



How do estimates behave?

Imagine repeating this process over and over, using the same survey design and a population drawn from the same density model

Each survey will yield:

A different value for n

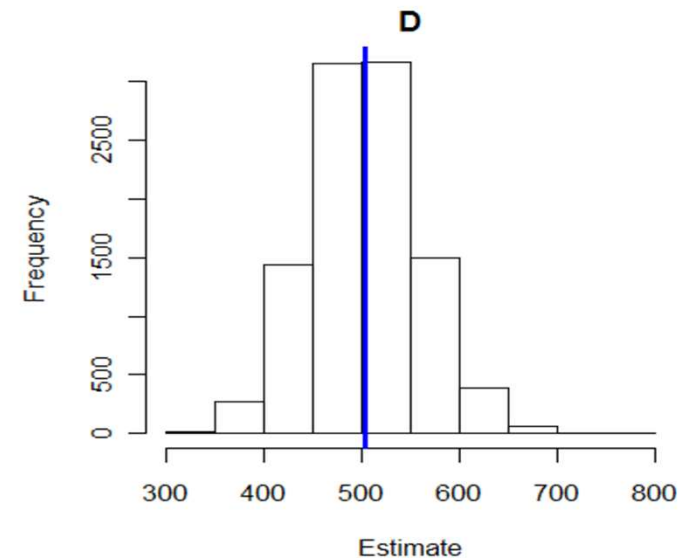
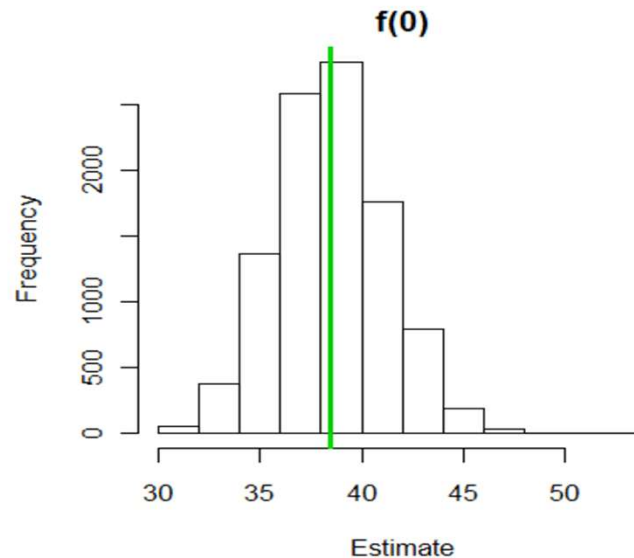
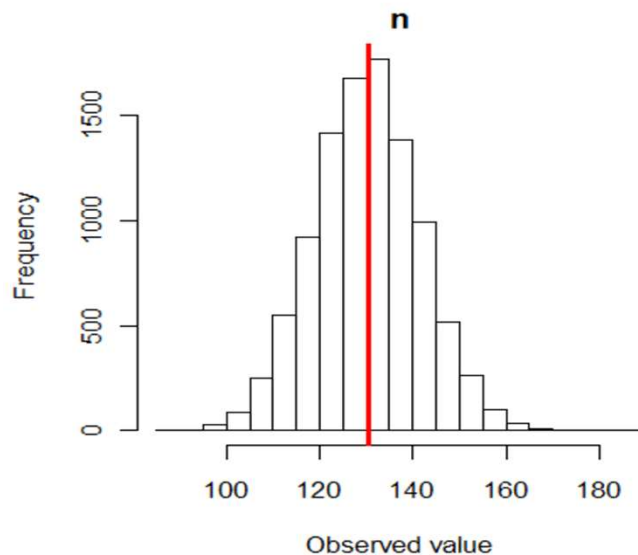
A different value for $\hat{f}(0)$

A different value for \hat{D}

How do estimates behave?

What happens if we repeat this simulated survey 10,000 times?

We end up with **distributions** for n , $\hat{f}(0)$ and \hat{D}



Note, $\hat{f}(0) = 1/w\hat{p}_a$

How do estimates behave?

We are interested in the **hypothetical long-run** behaviour of our estimator

$$\hat{D} = \frac{n}{2wL\hat{P}_a}$$

How variable are the estimates?

E.g. what is the variance of the distribution for \hat{D} ?

What is the average value of the estimates?

E.g. is the distribution for \hat{D} centred on the truth?

Quantifying uncertainty

Different ways of measuring uncertainty:

1. **Variance** = the average squared difference from the mean (the inverse of precision)

If the estimator for D is unbiased, then

$$Var[\hat{D}] = E[(\hat{D} - D)^2]$$

2. **Standard error** = the standard deviation of an estimator (i.e. the square root of estimator variance)

$$Se[\hat{D}] = \sqrt{Var[\hat{D}]}$$

Quantifying uncertainty

3. **Coefficient of Variation (CV)** = the standard error divided by the mean (i.e. a standardised version of the standard error)

$$CV[\hat{D}] = \frac{Se[\hat{D}]}{E[\hat{D}]}$$

Useful for comparing variances when the scale and/or the units of measurement differ

E.g. consider two variables: X has mean = 100 and variance = 400,
Y has mean = 1 and variance = 0.04

$$CV[X] = \frac{\sqrt{400}}{100} = \frac{20}{100} = 0.2 = 20\% \quad CV[Y] = \frac{\sqrt{0.04}}{1} = \frac{0.2}{1} = 0.2 = 20\%$$

Quantifying uncertainty

4. **Confidence Interval (CI)** = a range of plausible values for the truth

Calculations are based on variance

Different ways to calculate CIs, depending on the data, e.g.

Normal

Lognormal (available in Distance)

Bootstrap (available in Distance)

More about CIs later...

Why is variance important?

- In a real survey, we use an estimator and the survey data to produce a single estimate for D
- If the estimator variance is low, then individual estimates are more likely to be close to the truth (assuming low bias)
- If estimator variance is high, then individual estimates are more likely to be far from the truth
- For reliable results, we want estimators with LOW variance (and low bias!)

Variance by components

We can break down the familiar distance sampling density estimator (for line transects with no clusters) into three components:

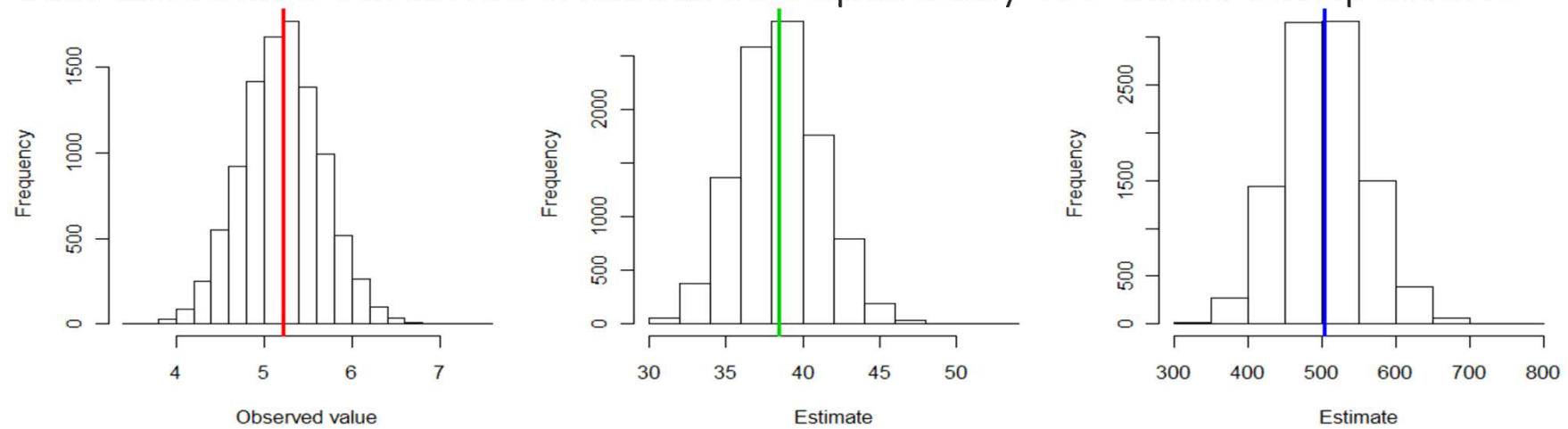
$$\hat{D} = \frac{n}{2wL\hat{P}_a} = \frac{1}{2w} \times \frac{n}{L} \times \frac{1}{\hat{P}_a}$$

Diagram illustrating the components of the density estimator \hat{D} :

- $\frac{1}{2w}$ is labeled "Constant (no variance)".
- $\frac{n}{L}$ is labeled "Encounter rate".
- $\frac{1}{\hat{P}_a}$ is labeled "Detection function".

Variance by components

We can calculate variance measures separately for each component



	n / L	$\hat{f}(0)$	\hat{D}
Mean	26.1	38.5	500.6
Se	2.27	2.71	56.34
CV	8.69 %	7.04 %	11.26 %

Variance by components

- The variance of \hat{D} is affected by the variance of its components
 - If the variance of n is high,
 - *then the variance of $\frac{n}{L}$ will be high and*
 - *the variance of \hat{D} will be high*
 - If the variance of \hat{P}_a is high
 - *then the variance of \hat{D} will be high*
- For reliable estimates,
 - we want $Var\left[\frac{n}{L}\right]$ and $Var[\hat{P}_a]$ to be low

Variance by components

Distance provides several variance measures for each component

	Estimate	SE	CV					
Average p	0.3491863	0.02160949	0.06188528					
N in covered region	300.6991117	30.11200030	0.10013997					
Summary statistics:								
Region	Area Covered	Area Effort	n	k	ER	se.ER	cv.ER	
1 Default	1	3436.8	48	105	12	2.1875	0.3169604	0.1448962
Abundance:								
Label	Estimate	se	cv	lcl	ucl	df		
1 Total	8.749392	1.378541	0.1575585	6.270328	12.20859	15.32522		
Density:								
Label	Estimate	se	cv	lcl	ucl	df		
1 Total	0.08749392	0.01378541	0.1575585	0.06270328	0.1220859	15.32522		

Controlling variance

- We can use this knowledge of encounter rate variance to help design good surveys
- Three main ways we can reduce encounter rate variance:
 - Use systematic survey designs
 - Run transects parallel to density gradients
 - Use designs with multiple transects

Estimating variance – Analytic

We can describe the relationship between the variance of \hat{D} and the variance of its components more formally using a useful approximation known as the **Delta method**

$$\{cv(\hat{D})\}^2 = \left\{cv\left(\frac{n}{L}\right)\right\}^2 + \{cv(\hat{P}_a)\}^2$$

Rule: when two or more components are multiplied together, **squared CVs add**

Estimating variance – Analytic

	$\frac{n}{L}$	$\hat{f}(0)$	\hat{D}
Mean	26.1	38.5	500.6
Se	2.27	2.71	56.34
CV	8.69 %	7.04 %	11.26 %

We can check this approximation works using the results of our simulation,

$$\{cv(\hat{D})\}^2 = 0.1126^2 = 0.01266$$

$$\left\{cv\left(\frac{n}{L}\right)\right\}^2 + \{cv(\hat{P}_a)\}^2 = 0.0869^2 + 0.0704^2 = 0.01251$$

We can rearrange the squared CV to get an estimate of the variance

$$var(\hat{D}) \approx \hat{D}^2 \times \{cv(\hat{D})\}^2$$

Estimating variance – Analytic

- To estimate $var(n/L)$ we need to use data from the individual lines (or points)
- A minimum of 20 replicate lines (or points) is recommended for obtaining a reliable estimate of encounter rate variance
- The formula used in Distance:

$$\left\{cv\left(\frac{n}{L}\right)\right\}^2 = \frac{k}{n^2(k-1)} \sum_{i=1}^k l_i^2 \left(\frac{n_i}{l_i} - \frac{n}{L}\right)^2$$

k = number of lines

l_i = effort for line i

n_i = count for line i

Estimating variance – Analytic

	Estimate	SE	CV					
Average p	0.3491863	0.02160949	0.06188528					
N in covered region	300.6991117	30.11200030	0.10013997					
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Component percentages of variance:		
.Label	Detection	ER
Total	15.43	84.57

Abundance and
Density always have
the same CV

Estimating variance – Analytic

	Estimate	SE	CV
Average p	0.3491863	0.02160949	0.06188528
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Component percentages of variance:

.Label	Detection	ER
Total	15.43	84.57

$$= \frac{0.0619^2}{0.1576^2} \times 100$$

$$= \frac{0.1449^2}{0.1576^2} \times 100$$

Estimating variance – Analytic

To find the **relative contributions** of each component we take the ratio of squared CVs

E.g. $100\% \times \frac{\{cv(\hat{P}_a)\}^2}{\{cv(\hat{D})\}^2} =$ The percentage relative contribution made by \hat{P}_a

Component	Typical values	
	Line	Point
Encounter rate	70-80%	40-50%
Detection function	<30%	>50%

Estimating variance – Bootstrap

- Works well if the original sample is **large and representative**
- The distribution of density estimates approximates the true distribution that we would (theoretically) get from duplicate surveys
- The variance of the bootstrap estimates can be used as an estimate of the true variance
- In Distance we **resample the individual transects**

Estimating variance – Bootstrap

- For example, consider a survey with 12 replicate lines
 - Bootstrap sample 1:
 - *Transects:* 5, 12, 1, 7, 6, 11, 7, 6, 9, 7, 11, 2
 - *Density estimate* = D_1
 - Bootstrap sample 2:
 - *Transects:* 3, 4, 9, 1, 12, 7, 8, 11, 1, 3, 2, 12
 - *Density estimate* = D_2
- Do this B times and use the variance of the B density estimates as an estimate of $var(\hat{D})$

Estimating variance – Bootstrap

Basic function to generate a bootstrap:

```
bootdht(model, flatfile, nboot, summary_fun)
```

`model` – detection function model

`flatfile` – data object used to fit model

`summary_fun` – function to harvest required statistic from each bootstrap sample

`nboot` – the number of bootstrap samples to use

Confidence Intervals

- Confidence intervals (CIs) give us a **range of plausible values** for the truth
- Constructed using data from a single sample
- If we were to carry out multiple surveys and construct 95% CIs from each survey, we would expect 95% of those CIs to contain the true value
- To calculate CIs, it would be beneficial to know the **shape** of the distribution of estimates

Confidence Intervals - Analytic

- Two choices:

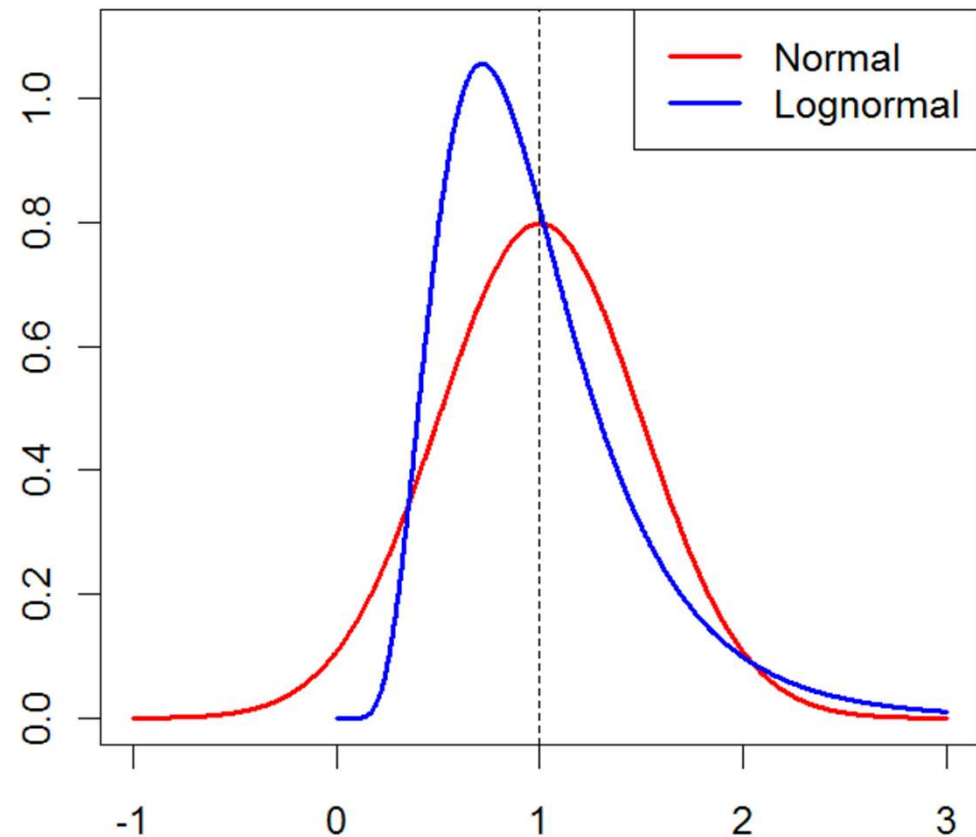
- Normal**

- symmetrical
- easy to use
- allows negative values

- Lognormal**

- asymmetric (skewed)
- trickier to use
- typically higher interval limits
- does not allow negative values

mean = 1, se = 0.5



Estimate

Confidence Intervals - Analytic

Distance uses 95% lognormal CIs

Abundance:

	Label	Estimate	se	cv	lcl	ucl	df
1	Total	8.749392	1.378541	0.1575585	6.270328	12.20859	15.32522

Density:

	Label	Estimate	se	cv	lcl	ucl	df
1	Total	0.08749392	0.01378541	0.1575585	0.06270328	0.1220859	15.32522

$$\left(\frac{\hat{D}}{\hat{C}}, \hat{D} \times C\right) \quad C = \exp \left[1.96 \sqrt{\ln \left\{ 1 + (cv(\hat{D}))^2 \right\}} \right]$$

Confidence Intervals – Bootstrap

The nonparametric option is provided in Distance

Bootstrap results

Boostraps : 999
Successes : 999
Failures : 0

	Estimate	se	ucl	lcl	cv
N	8.58	1.44	11.67	5.94	0.17
D	0.09	0.01	0.12	0.06	0.17

Standard error divided
by the mean

Further reading about precision

- Section 3.6 of Buckland et al. (2001) Introduction to Distance Sampling
- Fewster et al. (2009) Estimating the encounter rate variance in distance sampling. Biometrics 65: 225-236.
- Sections 6.3.1.2 and 6.3.2.2 of Buckland et al. (2015) Distance Sampling: Methods and Applications.

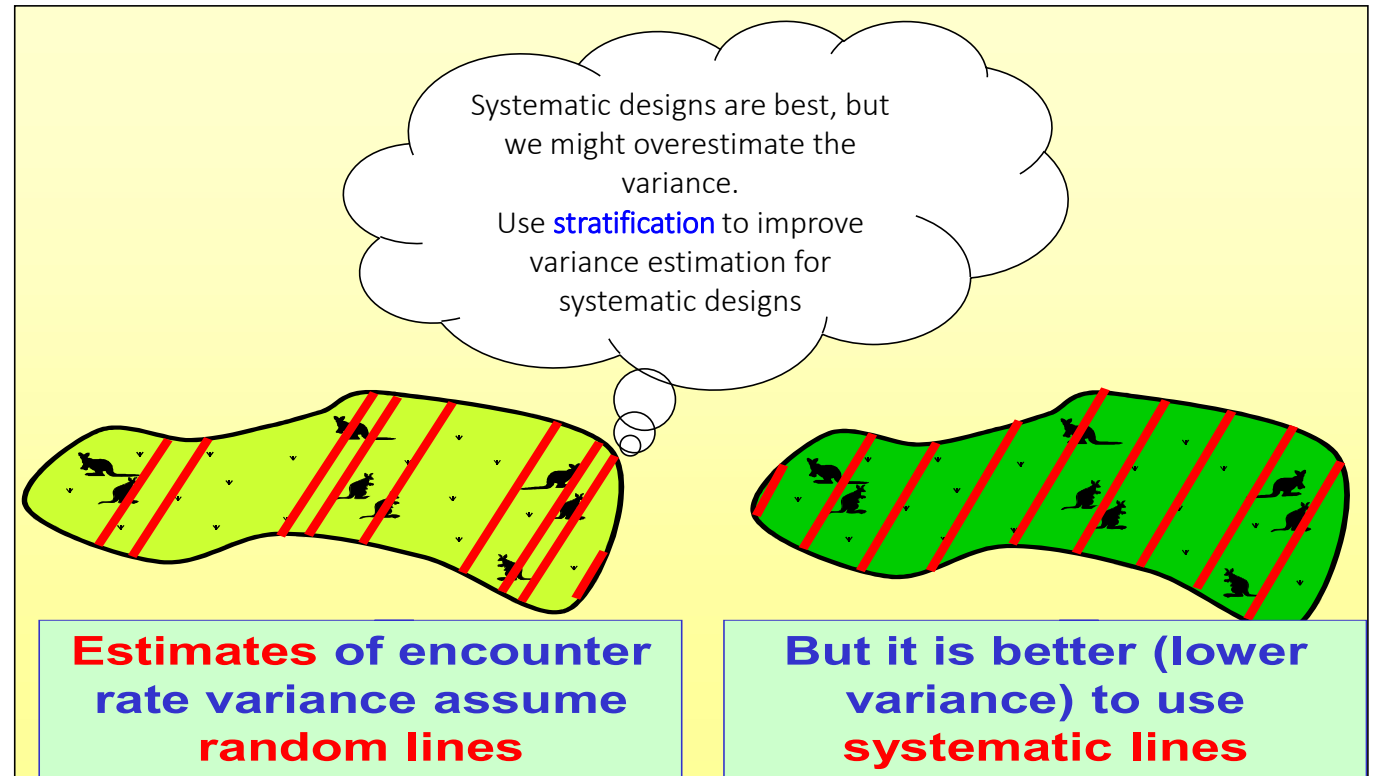
Producing a better estimate of variance when systematic samplers are used

- Fewster, RM, Buckland, ST, Burnham, KP, Borchers, DL, Jupp, PE, Laake, JL, and Thomas, L. 2009. Estimating the encounter rate in distance sampling. Biometrics 65: 225-236.

Systematic samples

Problem:

Systematic designs give the best variance, but the worst variance estimation!

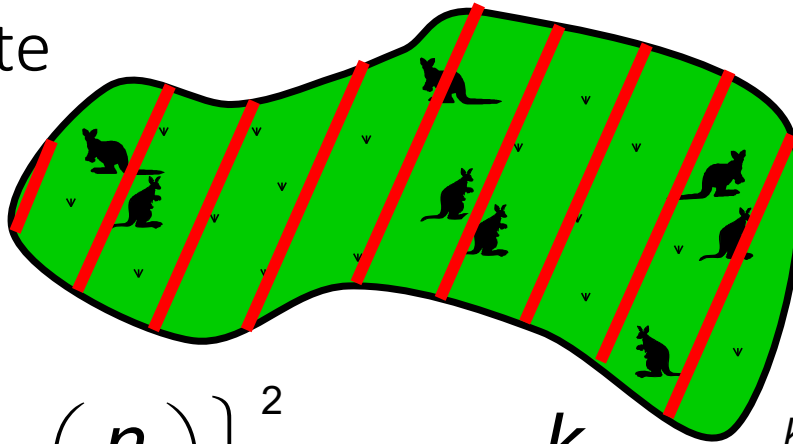


No unbiased estimator exists for estimating variance from a single systematic sample

Systematic samples advice

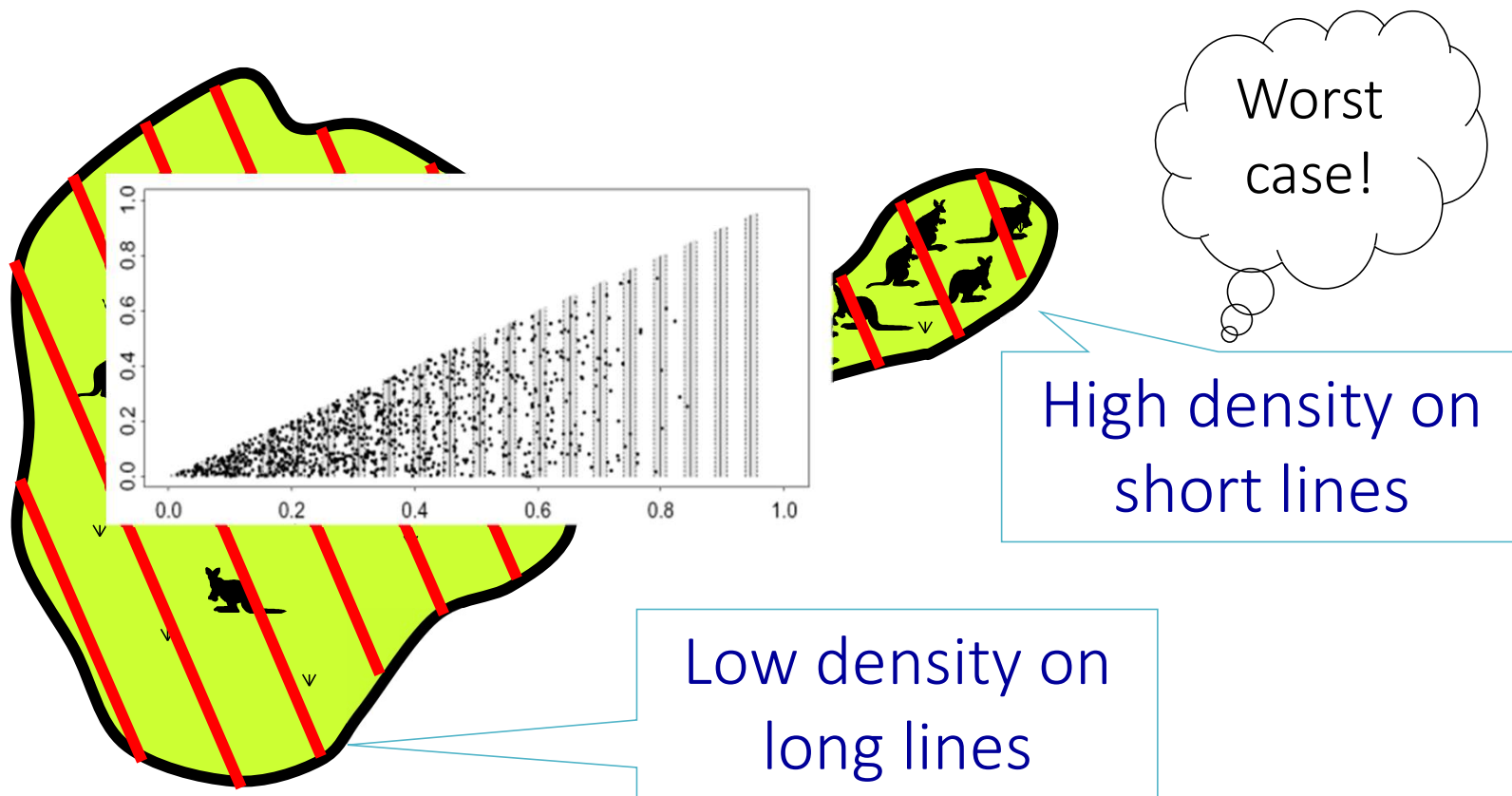
Usually, do nothing!

Variance estimation based on random lines will not be perfect, but adequate

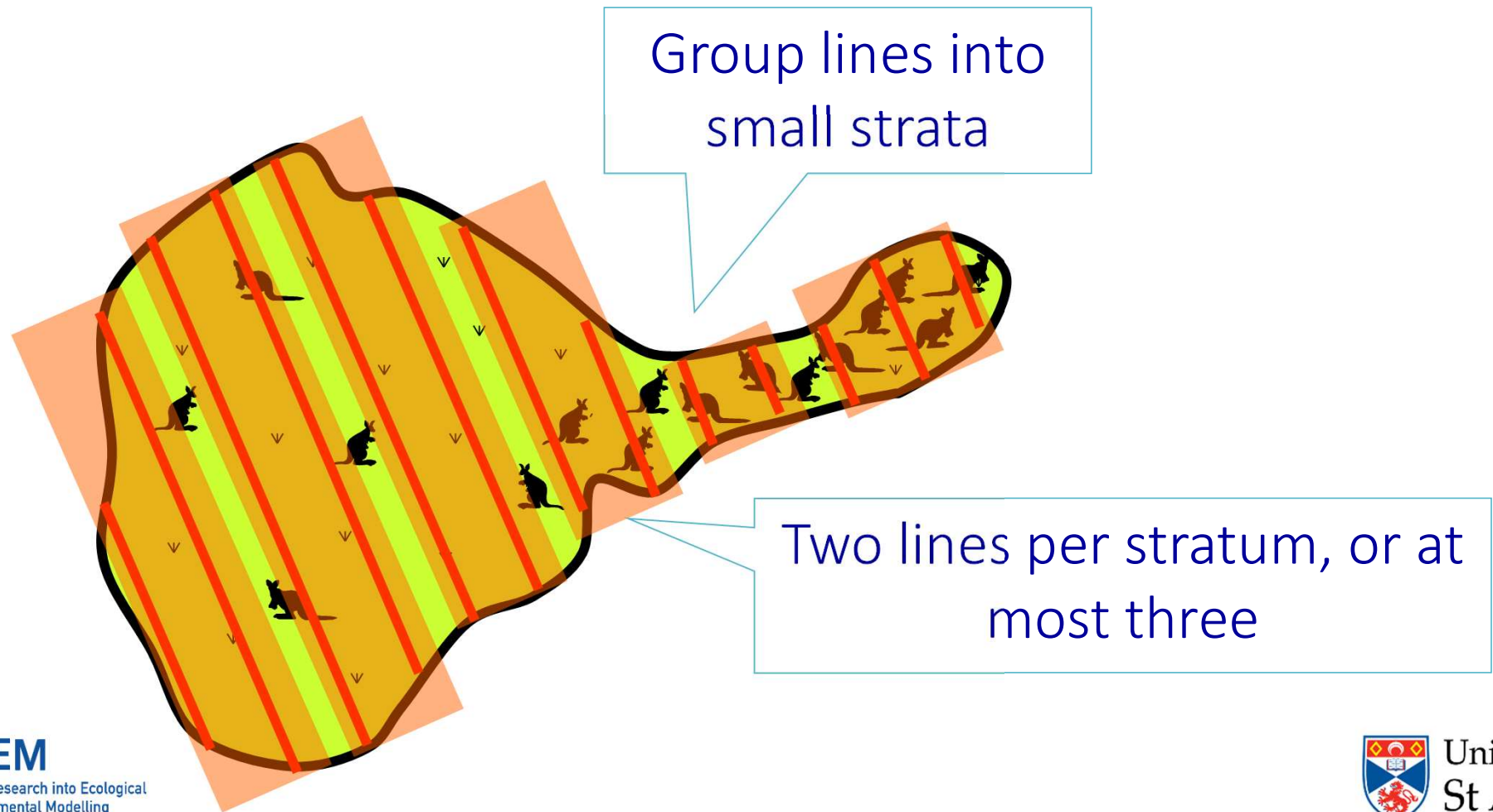


$$\left\{ cv \left(\frac{n}{L} \right) \right\}^2 = \frac{k}{n^2 (k - 1)} \sum_{i=1}^k \ell_i^2 \left(\frac{n_i}{\ell_i} - \frac{n}{L} \right)^2$$

If there are strong trends, variance might be significantly overestimated



Post-stratification can give much better variance estimates



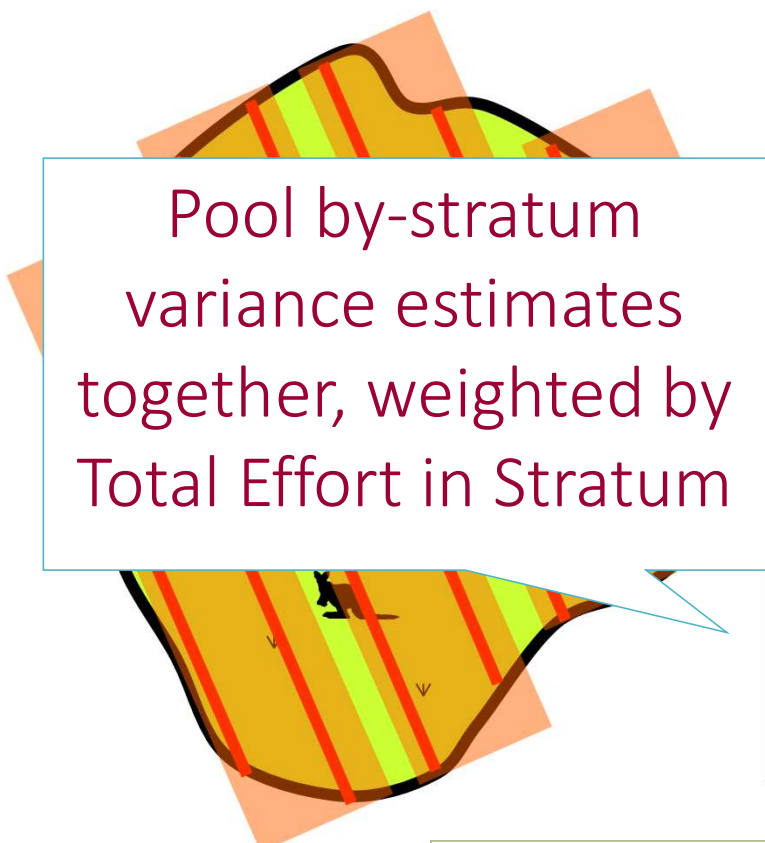
In Distance:

The encounter rate variance can be specified in the `dht2` function with the `er_est` argument

```
dht2(model, flatfile, er_est)
```

- The options follow the notation used in Fewster *et al.* (2009)
- The default is `er_est="R2"` – random line placement with unequal line length
- For systematic estimators, successive pairs of lines will be grouped together, according to the Sample.Label and so labels should be numeric (e.g. lines 1 and 2 grouped)
- If there are an odd number of lines, the last 3 will be grouped

Post-stratification can give much better estimates of variance



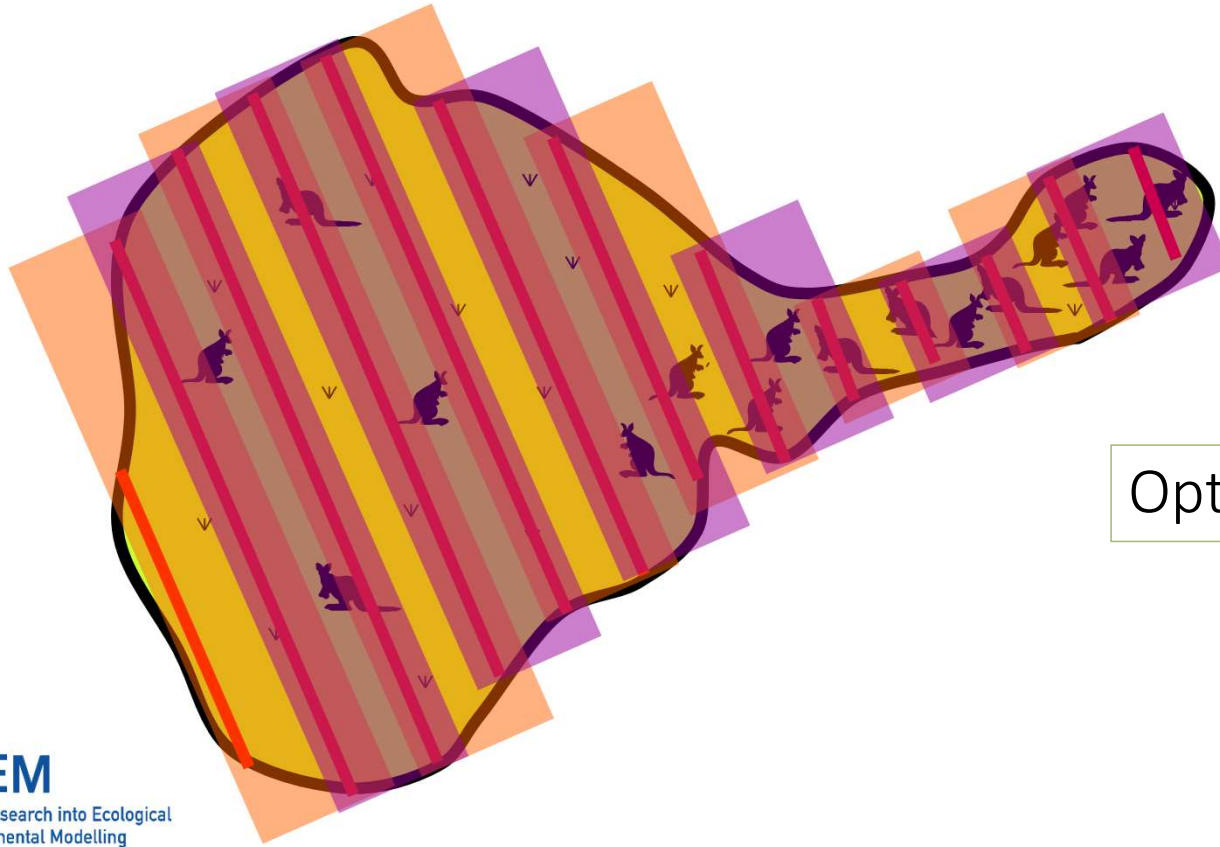
Pool by-stratum
variance estimates
together, weighted by
Total Effort in Stratum

Trends **within** strata are minor;
Estimate encounter rate variance
separately for each stratum

$$\hat{\text{var}}\left(\frac{n}{L}\right) = \frac{1}{L^2} \sum_{h=1}^H L_h^2 \hat{\text{var}}_h\left(\frac{n_h}{L_h}\right)$$

Option is `er_est="S2"`

Overlapping strata are even better, as you get a larger sample size of post-strata



Option is `er_est="02"`

Point transect surveys

Default (and only) option is `er_est="P2"`

